



SIMATIC ET 200SP, digital input module, DI 8x 24 V DC High Speed, Pack quantity: 1 unit, three alternative operating modes: DI, Oversampling, 4x counters, suitable for BU type A0, Color code CC01

General information	
Product type designation	DI 8x24 V DC HS
HW functional status	from FS04
Firmware version	
• FW update possible	Yes
usable BaseUnits	BU type A0
Color code for module-specific color identification plate	CC01
Product function	
• I&M data	Yes; I&M0 to I&M3
• Isochronous mode	Yes
Engineering with	
• STEP 7 TIA Portal configurable/integrated from version	V13 SP1
• STEP 7 configurable/integrated from version	V5.5 SP3 / -
• PROFIBUS from GSD version/GSD revision	One GSD file each, Revision 3 and 5 and higher
• PROFINET from GSD version/GSD revision	GSDML V2.3
Operating mode	
• DI	Yes
• Counter	Yes
• Oversampling	Yes
• MSI	No
Supply voltage	
Rated value (DC)	24 V
permissible range, lower limit (DC)	19.2 V
permissible range, upper limit (DC)	28.8 V
Reverse polarity protection	Yes
Input current	
Current consumption, max.	70 mA; without sensor supply
Encoder supply	
24 V encoder supply	
• 24 V	Yes
• Short-circuit protection	Yes; per module, electronic
• Output current, max.	700 mA
Power loss	
Power loss, typ.	1.5 W
Address area	
Address space per module	

<ul style="list-style-type: none"> <li>• Address space per module, max.</li> </ul>	45 byte
<ul style="list-style-type: none"> <li>• Inputs</li> </ul>	32 byte; 1 byte + 1 byte for QI information in DI mode; 32 bytes in Oversampling mode; 25 bytes in Counter mode
<ul style="list-style-type: none"> <li>• Outputs</li> </ul>	20 byte; In count mode
<b>Hardware configuration</b>	
Automatic encoding	Yes
<ul style="list-style-type: none"> <li>• Mechanical coding element</li> </ul>	Yes
<ul style="list-style-type: none"> <li>• Type of mechanical coding element</li> </ul>	Type A
<b>Selection of BaseUnit for connection variants</b>	
<ul style="list-style-type: none"> <li>• 1-wire connection</li> </ul>	BU type A0
<ul style="list-style-type: none"> <li>• 2-wire connection</li> </ul>	BU type A0
<ul style="list-style-type: none"> <li>• 3-wire connection</li> </ul>	BU type A0 with AUX terminals
<ul style="list-style-type: none"> <li>• 4-wire connection</li> </ul>	BU type A0 + external terminals
<b>Digital inputs</b>	
Number of digital inputs	8
Source/sink input	P-reading
Pulse extension	Yes
<ul style="list-style-type: none"> <li>• Length</li> </ul>	2 s; 50 ms, 100 ms, 200 ms, 500 ms, 1 s, 2 s
<b>Digital input functions, parameterizable</b>	
<ul style="list-style-type: none"> <li>• Gate start/stop</li> </ul>	Yes
<ul style="list-style-type: none"> <li>• Freely usable digital input</li> </ul>	Yes
<ul style="list-style-type: none"> <li>• Counter</li> </ul>	Yes
<ul style="list-style-type: none"> <li>— Number, max.</li> </ul>	4
<ul style="list-style-type: none"> <li>— Counting frequency, max.</li> </ul>	10 kHz
<ul style="list-style-type: none"> <li>— Counting width</li> </ul>	32 bit
<ul style="list-style-type: none"> <li>— Counting direction up/down</li> </ul>	Yes
<ul style="list-style-type: none"> <li>• Digital input with oversampling</li> </ul>	Yes
<ul style="list-style-type: none"> <li>— Number, max.</li> </ul>	8
<ul style="list-style-type: none"> <li>— Values per cycle, max.</li> </ul>	32
<ul style="list-style-type: none"> <li>— Resolution, min.</li> </ul>	7.8125 $\mu$ s
<b>Input voltage</b>	
<ul style="list-style-type: none"> <li>• Rated value (DC)</li> </ul>	24 V
<ul style="list-style-type: none"> <li>• for signal "0"</li> </ul>	-30 to +5 V
<ul style="list-style-type: none"> <li>• for signal "1"</li> </ul>	+11 to +30V
<b>Input current</b>	
<ul style="list-style-type: none"> <li>• for signal "1", typ.</li> </ul>	6 mA
<b>Input delay (for rated value of input voltage)</b>	
for standard inputs	
<ul style="list-style-type: none"> <li>— parameterizable</li> </ul>	Yes; none / 0.05 / 0.1 / 0.4 / 0.8 / 1.6 / 3.2 / 12.8 / 20 ms
for interrupt inputs	
<ul style="list-style-type: none"> <li>— parameterizable</li> </ul>	Yes
for technological functions	
<ul style="list-style-type: none"> <li>— parameterizable</li> </ul>	Yes
<b>Cable length</b>	
<ul style="list-style-type: none"> <li>• shielded, max.</li> </ul>	50 m
<ul style="list-style-type: none"> <li>• unshielded, max.</li> </ul>	50 m
<b>Encoder</b>	
<b>Connectable encoders</b>	
<ul style="list-style-type: none"> <li>• 2-wire sensor</li> </ul>	Yes
<ul style="list-style-type: none"> <li>— permissible quiescent current (2-wire sensor), max.</li> </ul>	1.5 mA
<b>Isochronous mode</b>	
Bus cycle time (TDP), min.	125 $\mu$ s
Jitter, max.	5 $\mu$ s
<b>Interrupts/diagnostics/status information</b>	
Diagnostics function	Yes
<b>Alarms</b>	
<ul style="list-style-type: none"> <li>• Diagnostic alarm</li> </ul>	Yes

• Hardware interrupt	Yes
<b>Diagnoses</b>	
• Diagnostic information readable	Yes
• Monitoring the supply voltage	Yes
— parameterizable	Yes
• Monitoring of encoder power supply	Yes; Module-wise
• Wire-break	No
• Short-circuit	Yes; Module-wise
<b>Diagnostics indication LED</b>	
• Monitoring of the supply voltage (PWR-LED)	Yes; green PWR LED
• Channel status display	Yes; green LED
• for channel diagnostics	No
• for module diagnostics	Yes; green/red DIAG LED
<b>Potential separation</b>	
<b>Potential separation channels</b>	
• between the channels	No
• between the channels and backplane bus	Yes
• between the channels and the power supply of the electronics	No
<b>Isolation</b>	
Isolation tested with	707 V DC (type test)
<b>Standards, approvals, certificates</b>	
Suitable for safety functions	No
<b>Ambient conditions</b>	
<b>Ambient temperature during operation</b>	
• horizontal installation, min.	-30 °C; < 0 °C as of FS04
• horizontal installation, max.	60 °C
• vertical installation, min.	-30 °C; < 0 °C as of FS04
• vertical installation, max.	50 °C
<b>Altitude during operation relating to sea level</b>	
• Installation altitude above sea level, max.	5 000 m; Restrictions for installation altitudes > 2 000 m, see manual
<b>Dimensions</b>	
Width	15 mm
Height	73 mm
Depth	58 mm
<b>Weights</b>	
Weight, approx.	28 g

**last modified:**